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S. No	Course Code	Course Name	L	T	P	C
		Semester - II				
1	MA 102	Linear Algebra	3	1	0	4
2	MA 103	Differential Equations -I	3	1	0	4
3	ME 111	Engineering Graphics Lab	1	0	3	5
4	EE 101	Introduction to Electrical Systems and Electronics	3	0	0	6
5	CS 201	Data Structures and Algorithms	3	0	0	6
6	CS 211	Data Structures and Algorithms Laboratory	0	0	3	3
7	ME 113	Hands on Engineering Lab	0	0	3	3
8	ME 201	Engineering Mechanics	2	1	0	6
9	NO107/ NO105/ NO 106/ NO 108	NSO/NSS/NCC/NCA	0	0	2	2
		Total Credits				37

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1	Title of the course (L-T-P-C)	Linear Algebra (3-1-0-4)
2	Pre-requisite courses(s)	--
3	Course content	Vectors in R^n, notion of linear independence and dependence, linear span of a set of vectors, vector subspaces of R^n, basis of a vector subspace. Systems of linear equations, matrices and Gauss elimination, row space, null space, and column space, rank of a matrix. Determinants and rank of a matrix in terms of determinants. Abstract vector spaces, linear transformations, matrix of a linear transformation, change of basis and similarity, rank-nullity theorem. Inner product spaces, Gram-Schmidt process, orthonormal bases, projections and least squares approximation. Eigenvalues and eigenvectors, characteristic polynomials, eigenvalues of special matrices (orthogonal, unitary, hermitian, symmetric, skew-symmetric, normal). Algebraic and geometric multiplicity, diagonalization by similarity transformations, spectral theorem for real symmetric matrices, application to quadratic forms.
4	Texts/References	1. H. Anton, Elementary linear algebra with applications (8th Edition), John Wiley (1995). 2. G. Strang, Linear algebra and its applications (4th Edition), Thomson (2006) 3. S. Kumaresan, Linear algebra - A Geometric approach, Prentice Hall of India (2000) 4. E. Kreyszig, Advanced engineering mathematics (10th Edition), John Wiley (1999)

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1	**Title of the course** (L-T-P-C)	**Differential Equations -I** **(3-1-0-4)**
2	**Pre-requisite courses(s)**	Nil
3	**Course content**	Exact equations, integrating factors and Bernoulli equations. Orthogonal trajectories. Lipschitz condition, Picard's theorem, examples on non-uniqueness. Linear differential equations generalities. Linear dependence and Wronskians. Dimensionality of space of solutions, Abel-Liouville formula. Linear ODE's with constant coefficients, the characteristic equations. Cauchy-Euler equations. Method of undetermined coefficients. Method of variation of parameters. Laplace transform generalities. Shifting theorems. Convolution theorem.
4	**Texts/References**	1. E. Kreyszig, Advanced engineering mathematics (10th Edition), John Wiley (1999) 2. W. E. Boyce and R. DiPrima, Elementary Differential Equations (8th Edition), John Wiley (2005)

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1	Title of the course (L-T-P-C)	**Engineering Graphics Lab** **(1-0-3-5)**
2	**Pre-requisite courses(s)**	--
3	**Course content**	Engineering Graphics with mini drafter: Around half a semester and bit more with following topics to be covered. • Introduction to Engineering Graphics • Curves • Projections of Points • Projection of Lines • Projection of Planes • Projections on Auxiliary Planes • Projections of Solids • Sections of Solids • Intersections of Solids Engineering Graphics with 2D Drafting Software: 5 weekly computer laboratory sessions covering above using AutoCAD® as a drafting software, 5th session on Isometric Projections.
4	**Texts/References**	1. N. D. Bhatt, revised and enlarged by V. M. Panchal and P. R. Ingle, Engineering Drawing, 53rd Edition, 2014, Charotar Publishers, Anand. 2. Warren J. Luzadder and Jon M. Duff, Fundamentals of Engineering Drawing, Prentice-Hall of India. 3. Gopalakrishna K. R., Engineering Drawing Vol. I & II Combined., Subhas Stores, 25th Edition, 2017. 4. Narayana. K. L., and Kannaiah, P. E., Text Book on Engineering Drawing, 2nd Edition, 2013, Scitech Publications, Chennai. 5. Venugopal K. and Prabhu Raja V., Engineering Drawing + AutoCAD, New Age International Publishers, 5th Edition, 2011.

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1	Title of the course (L-T-P-C)	Introduction to Electrical Systems and Electronics (3-0-1-6)
2	Pre-requisite courses(s)	Exposure to Calculus
3	Course content	**From Physics to Electrical Engineering** (a) Lumped matter discipline (b) Batteries, resistors, current sources and basic laws (c) I-V characteristics and modeling physical systems **Basic Circuit Analysis Methods** (a) KCL and KVL, voltage and current dividers (b) Parallel and serial resistive circuits (c) More complicated circuits (d) Dependent sources, and the node method (e) Superposition principle (f) Thevenin and Norton method of solving linear circuits (g) Circuits involving diode. **Analysis of Non-linear Circuits** (a) Toy example of non-linear circuit and its analysis (b) Incremental analysis (c) Introduction to MOSFET Amplifiers (d) Large and small signal analysis of MOSFETs (e) MOSFET as a switch **Introduction to the Digital World** (a) Voltage level and static discipline (b) Boolean logic and combinational gates (c) MOSFET devices and the S Model (d) MOSFET as a switch; revisited (e) The SR model of MOSFETs (f) Non-linearities: A snapshot **Capacitors and Inductors** (a) Behavior of capacitors, inductors and its linearity (b) Basic RC and RLC circuits (c) Modeling MOSFET anomalies using capacitors (d) RLC circuit and its analysis (e) Sinusoidal steady state analysis (f) Introduction to passive filters **Operational Amplifier Abstraction** (a) Introduction to Operational Amplifier (b) Analysis of Operational amplifier circuits (c) Op-Amp as active filters (d) Introduction to active filter design **Transformers and Motors** (a) AC Power circuit analysis (b) Polyphase circuits (c) Introduction to transformers (d) Introduction to motors

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4	Texts/References	1. Anant Agarwal and Jefferey H. Lang, "Foundations of Analog and Digital Electronics Circuits," Morgan Kaufmann publishers, 2005 2. Wlilliam H. Hayt, Jr., Jack E. Kemmerly and Steven M. Durbin, "Engineering Circuit Analysis," Tata McGraw-Hill 3. Theodore Wildi, "Electrical Machines, Drives and Power Systems," Pearson, 6-th edition. 4. V. Del. Toro, "Electrical Engineering Fundamentals," Pearson publications, 2nd edition.

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1	**Title of the course** (L-T-P-C)	**Data Structures and Algorithms** **(3-0-0-6)**
2	**Pre-requisite courses(s)**	Exposure to Computer Programming
3	**Course content**	Introduction: data structures, abstract data types,analysis of algorithms. Creation and manipulation of data structures: arrays,lists, stacks, queues, trees, heaps, hash tables, balanced trees, tries, graphs. Algorithms for sorting and searching, order statistics, depth-first and breadth-first search, shortest paths and minimum spanning tree.
4	**Texts/References**	1. Introduction to Algorithms, 3rd edition, by T. Cormen, C. Leiserson, R. Rivest, C. Stein, MIT Pressand McGraw-Hill, 2009. 2. Data structures and algorithms in C++, by Michael T. Goodrich, Roberto Tamassia, and David M. Mount,Wiley, 2004.

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1	Title of the course (L-T-P-C)	**Data Structures and Algorithms Laboratory** **(0-0-3-3)**
2	**Pre-requisite courses(s)**	Exposure to Computer Programming (CS 102)
3	**Course content**	Laboratory course for CS 211 is based on creatingand manipulating various data structures and implementation of algorithms.
4	**Texts/References**	1. Introduction to Algorithms, 3rd edition, by T. Cormen, C. Leiserson, R. Rivest, C. Stein, MIT Pressand McGraw-Hill, 2009. 2. Data structures and algorithms in C++, by Michael T.Goodrich, Roberto Tamassia, and David M. Mount, Wiley, 2004.

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1	**Title of the course** (L-T-P-C)	**Hands on Engineering Lab** **(0-0-3-3)**
2	**Pre-requisite courses(s)**	--
3	**Course content**	**List of Experiments (Mechanical Workshop)** • To make a Square-fit from the given mid steel pieces (Fitting) • To make a V-fit from the given mid steel pieces (Fitting) • To make a rectangular tray as per required dimensions (Sheet Metal) • To build a transition piece (Sheet Metal) • To make a Butt joint using the given two M.S pieces (Arc welding) • To make a lap joint using the given two M.S pieces (Arc welding) • To build a pipe-line using fittings for given flow circuit (Plumbing) **List of Experiments (Electrical Workshop)** • To control one lamp by a one switch with provision for plug socket with switch control (Electrical wiring) • To do stair case wiring (i.e. control of one lamp by two switches fixed at two different places) (Electrical wiring) • Measurement of hot and cold resistance of filament • Improvement of Power Factor • Calibration of Energy meter • Measurement of Power using three ammeter/voltmeter method **List of Experiments (Electronics)** • Understanding breadboard, One-way traffic • Introduction to Arduino and Buzzer • Using Arduino speed measurement of motor/ glowing of LED • Control of water level using Arduino Line follower using Arduino
4	**Texts/References**	Elements of Workshop Technology Vol. 1 (2015), S. K. Hajra Choudhary, A. K. Hajra Choudhary and Nirjhar Roy, Media Promoters and Publishers Pvt. Ltd. W. A. J. Chapman, Workshop Technology, Vol. 1 (2006), Vol 2 (2007), and (1995), CBS Publishers.

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1	**Title of the course** (L-T-P-C)	**Engineering Mechanics** **(2-1-0-6)**
2	**Pre-requisite courses(s)**	--
3	**Course content**	**Module 1:** Introduction to Engineering Mechanics covering, Force Systems Basic concepts, Particle equilibrium in 2-D & 3-D; Rigid Body equilibrium; System of Forces, CoplanarConcurrent Forces, Components in Space – Resultant-Moment of Forces and its Application; Couples and Resultant of Force System, Equilibrium of System of Forces, Free body diagrams, Equations of Equilibrium of Coplanar Systems and Spatial Systems; Static Indeterminacy. **Module 2:** Friction covering, Types of friction, Limiting friction, Laws of Friction, Static and Dynamic Friction; Motion of Bodies, wedge friction, screw jack & differential screw jack. **Module 3:** Basic Structural Analysis covering, Equilibrium in three dimensions; Method of Sections; Method of Joints; How to determine if a member is in tension or compression; Simple Trusses; Zero force members; Beams & types of beams; Frames & Machines. **Module 4:** Centroid and Centre of Gravity covering, Centroid of simple figures from first principle, centroid of composite sections; Centre of Gravity and its implications; Area moment of inertia- Definition, Moment of inertia of plane sections from first principles, Theorems of moment of inertia, Moment of inertia of standard sections and composite sections; Mass moment inertia of circular plate, Cylinder, Cone, Sphere, Hook. **Module 5:** Virtual Work and Energy Method- Virtual displacements, principle of virtual work for particle and ideal system of rigid bodies, degrees of freedom. Active force diagram, systems with friction, mechanical efficiency. Conservative forces and potential energy (elastic and gravitational), energy equation for equilibrium. Applications of energy method for equilibrium. Stability of equilibrium. **Module 6:** Particles dynamics- Kinematics of Particles: Rectilinear motion, Plane curvilinear motion - rectangular coordinates, normal and tangential coordinates, polar coordinates, Space curvilinear - cylindrical, spherical (coordinates), Relative and Constrained motion. Kinetics of Particles: Force, mass and acceleration – rectilinear and curvilinear motion, work and energy, impulse and momentum – linear and angular; Impact – Direct and Oblique. Kinetics of System of Particles: Generalized Newton's Second Law, Work-Energy, Impulse-Momentum, Conservation of Energy and Momentum. **Module 7:** Introduction to Rigid body dynamics Kinematics of Planar Rigid Bodies: Equations for rotation of a rigid body about a fixed axis, General plane motion, Instantaneous Center of Rotation in Plane Motion Plane Motion of a Particle Relative to a Rotating Frame. Coriolis Acceleration Kinetics of Planar Rigid Bodies: Equations of Motion for a Rigid Body, Angular Momentum of a Rigid Body in Plane

		Motion, Plane Motion of a Rigid Body and D'Alembert's Principle, Systems of Rigid Bodies, Constrained Plane Motion; Energy and Work of Forces Acting on a Rigid Body, Kinetic Energy of a Rigid Body in Plane Motion, Systems of Rigid Bodies, Conservation of Energy, Plane Motion of a Rigid Body - Impulse and Momentum, Systems of Rigid Bodies, Conservation of Angular Momentum. **Module 8:** Mechanical Vibrations covering, Basic terminology, free and forced vibrations, resonance and its effects; Degree of freedom; Derivation for frequency and amplitude of free vibrations without damping and single degree of freedom system, simple problems, types of pendulums, use of simple, compound and torsion pendulums
4	**Texts/References**	**Textbooks:** 1. J. L. Meriam and L. G. Kraige, Engineering Mechanics, Vol I – Statics, Vol II – Dynamics, 6th Ed, John Wiley, 2008. 2. F. P. Beer and E. R. Johnston, Vector Mechanics for Engineers, Vol I - Statics, Vol II – Dynamics, 9th Ed, Tata McGraw Hill, 2011. 3. R. C. Hibbler, Engineering Mechanics: Principles of Statics and Dynamics, Pearson Press, 2006. **References:** 1. S. P. Timoshenko and D. H. Young, Engineering Mechanics. Fourth Edition. McGraw-Hill, New York, 1956. 2. I. H. Shames, Engineering Mechanics: Statics and dynamics, 4th Ed, PHI, 2002. 3. Robert W. Soutas-Little; Daniel J. Inman; Daniel Balint, Engineering Mechanics: Dynamics – Computational Edition, 1st Ed., Cengage Learning, 2007. 4. Robert W. Soutas-Little; Daniel J. Inman; Daniel Balint, Engineering Mechanics: Statics-Computational Edition, 1st Ed., ,Cengage Learning, 2007

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